

CLAIMS

What is claimed is:

1. An in-vivo system comprising:
an in vivo device, said device comprising:
 - 5 an illumination source and a detector to collect reflected light; and
 - a processor to, based on signals from the detector, determine a location of the in-vivo device.
2. The system according to claim 1, wherein said detector is configured to receive light from a body lumen wall.
- 10 3. The system according to claim 1, wherein said processor is configured to indicate a movement of said in-vivo device from one area to another.
4. The system according to claim 1, wherein said processor is configured to indicate a movement from a relatively small diameter lumen into a larger diameter lumen.
- 15 5. The system according to claim 1 wherein the in vivo device comprises an imager.
6. The system according to claim 5, wherein said detector is located at a location of said in-vivo device such that illumination generated from said illumination source and reflected from a body lumen wall to said detector is not received at
20 the imager.
7. The system according to claim 1, wherein said detector is selected from the group consisting of: a CMOS, a CCD and a photodiode.
8. The system according to claim 1, comprising a primary light source and a dedicated light source.
- 25 9. The system according to claim 8 wherein the primary light source illuminates a body lumen for imaging said body lumen and wherein the dedicated light source illuminates a body lumen for locating the in vivo device.

10.The system according to claim 8 wherein the primary light source is positioned behind an optical window in the in vivo device.

11.The system according to claim 5, wherein said imager is a detector.

12.The system according to claim 1, wherein said processor is disposed within said
5 in-vivo device.

13.The system according to claim 1, wherein said processor is external to the in-vivo device

14.The system according to claim 1, wherein said processor is a controller.

15.The system according to claim 1, comprising a controller, wherein said
10 controller is configured to receive signals from said detector and to trigger an event to occur within said in-vivo device.

16.The system according to claim 1 comprising a transmitter.

17.The system according to claim 1, wherein said in-vivo device is a swallowable capsule.

15 18.A method for locating an in vivo device, the method comprising;
illuminating a body lumen wall;
receiving light reflected from the body lumen wall;
determining a location of the in vivo device, based on comparing received light to a predetermined threshold.

20 19.The method according to claim 18 comprising:
transmitting light from behind an optical window in an in-vivo sensing device; the window shielding an imager;
receiving reflected light by a detector, wherein said detector does not detect light through said optical window ; and
25 determining the location of the device, based on comparing received light to a predetermined threshold.

20.The method according to claim 18, wherein said comparing comprises comparing the quality of said reflected light to a predetermined threshold.

21.The method according to claim 18, wherein said comparing comprises comparing the quantity of said reflected light to a predetermined threshold.

22.The method according to claim 18, comprising sending a signal if a change in said reflected light is determined, to a unit selected from the group consisting of:
5 a reception unit, a processing unit and an operator unit.

23.The method according to claim 18, comprising initiating an event if there is a change in said reflected light according to a comparison to the pre-determined threshold.

24.The method according to claim 18, comprising changing a mode of operation if
10 there is a change in said reflected light according to a pre-determined threshold.

25.The method according to claim 18 comprising:

transmitting light from a dedicated light source in an in-vivo sensing device,
wherein said dedicated light source is located so as not to illuminate through an
optical window of said device;
15 receiving reflected light by a detector; and
determining the location of the device, based on comparing received light to a
predetermined threshold.

26.The method according to claim 18, comprising initiating a mode change based on comparing received light to a predetermined threshold.

20 27.The method according to claim 26 wherein said mode change includes a change selected from the group consisting of: commanding said device to transmit images, instructing said device to deliver medication or take samples, changing the focus of an imager, releasing a chemical and shutting down or pausing imaging.

25 28.The method according to claim 18, comprising changing a mode of operation based on comparing received light to a predetermined threshold.